

Lecture 2

Lecturer: Haim Permuter

Scribe: Amit Toren and Liran Mishali

I. RATE DISTORTION

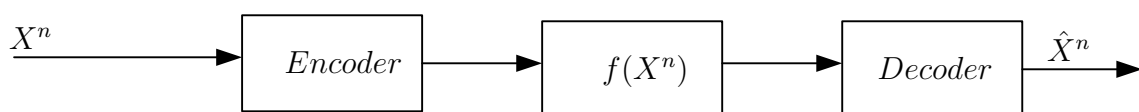


Fig. 1. Communication system

Definition 1 (Distortion function.) A distortion function or distortion measure is a mapping

$$d : \mathcal{X} \times \hat{\mathcal{X}} \rightarrow \mathcal{R}^+ \quad (1)$$

from the set of source alphabet-reproduction alphabet pairs into the set of nonnegative real numbers. The distortion $d(x, \hat{x})$ is a measure of the cost of representing the symbol x by the symbol \hat{x} .

Definition 2 (Distortion Bound.) A distortion measure is said to be bounded if the maximum value of the distortion is finite:

$$d_{max} \stackrel{def}{=} \max_{x \in \mathcal{X}, \hat{x} \in \hat{\mathcal{X}}} d(x, \hat{x}) < \infty. \quad (2)$$

In most cases, the reproduction alphabet $\hat{\mathcal{X}}$ is the same as the source alphabet \mathcal{X} .

Example 1 : Examples of common distortion function are:

$$d(X_i, \hat{X}_i) = X_i \oplus \hat{X}_i - \text{Hamming Distance}$$

$$d(X_i, \hat{X}_i) = (X_i - \hat{X}_i)^2 - \text{Mean Square Error}$$

Definition 3 (Distortion between sequences) The distortion between sequences x^n and \hat{x}^n is defined by:

$$D(x^n, \hat{x}^n) = \frac{1}{n} \sum_{i=1}^n d(x_i, (\hat{x}_i)). \quad (3)$$

Hence, the distortion for a sequence is the average of the per symbol distortion of the elements of the sequence.

Definition 4 ($(2^{nR}, n)$ -rate distortion code) A $(2^{nR}, n)$ -rate distortion code consists of:

- Encoder: $f(X^n) : X^n \mapsto (1, 2, 3, \dots, 2^{nR})$
- Decoder: $g(f(X^n)) : (1, 2, 3, \dots, 2^{nR}) \mapsto \hat{X}^n$

The distortion associated with the $(2^{nR}, n)$ code is defined as $E[D(X^n, \hat{X}^n)] = \frac{1}{n} \sum_{i=1}^n E[d(X_i, \hat{X}_i)]$

Definition 5 (Achievable Rate.) A rate distortion pair (R, D) is *achievable* if there exists a sequence of $(n, 2^{nR})$ codes s.t : $\lim_{n \rightarrow \infty} E[D(X^n, \hat{X}^n)] \leq D$

Definition 6 (Rate Distortion function $R(D)$) Given a distortion D , *rate distortion function* $R(D)$ is the infimum of all achievable rates with Distortion D

Definition 7 (Distortion Rate function $D(R)$) Given a rate R , the *distortion rate function* $D(R)$ is the infimum of all distortion D such that (R, D) is in the rate distortion region.

Let us define the mathematical measure $R^{(I)}(D)$ as

$$R(D)^{(I)} = \min_{p(\hat{x}|x): E(d(x, \hat{x})) \leq D} I(X; \hat{X}), \quad (4)$$

where the minimization is over all conditional distributions $P(\hat{x}|x)$ for which the joint distribution $P(x, \hat{x}) = P(x)P(\hat{x}|x)$ satisfies the expected distortion constrained.

Theorem 1 The rate distortion function function an i.i.d. source $X \sim P_X$ and bounded distortion function $d(x, \hat{x})$ is equal to

$$R(D) = R^{(I)}(D) = \min_{p(x; \hat{x}): \sum_{(x, \hat{x})} p(x)p(\hat{x}|x)d(x, \hat{x}) \leq D} I(X; \hat{X}) \quad (5)$$

A. CALCULATION OF THE RATE DISTORTION FUNCTION

1) Binary Source:

Example 2 Consider the rate distortion function for a Bernoulli(p) source with Hamming distortion. Mathematically, $X \sim \text{Ber}(p)$, $p \leq \frac{1}{2}$, $D \leq \frac{1}{2}$, $d(x_i, \hat{x}_i) = x_i \oplus \hat{x}_i$. What is the rate distortion function, $R(D)$?

Solution

$$R(D) = \begin{cases} H_b(p) - H(D) & p > D \\ 0 & p < D \end{cases}$$

Note that if $D = 0$ then $X = \hat{X}$ and we obtain the well known result of lossless compression $R = H_b(p)$

Now, let's show that this is the best we can do (upper bound):

$$\begin{aligned} I(X; \hat{X}) &= H(X) - H(X|\hat{X}) \\ &= H(X) - H(X \oplus \hat{X}_i | \hat{X}) \\ &\geq H(X) - H(X \oplus \hat{X}_i) \\ &\geq H_b(p) - H_b(D). \end{aligned}$$

We will achieve it with: $\hat{X} \sim \text{Ber}(p_0)$, $Z \sim \text{Ber}(D)$, $Z \perp \hat{X}$ and $X = \hat{X} \oplus Z$ where $X \sim \text{Ber}(p)$. The relation

$$p_0 * D \triangleq p_0(1 - D) + (1 - p_0)D = p \quad (6)$$

should hold. It implies $p_0 = \frac{p-D}{1-2D}$. Note that if $\frac{1}{2} \geq p > D$ such p_0 exists.

$$\begin{aligned} I(X; \hat{X}) &= H(X) - H(X|\hat{X}) \\ &= H(X) - H(X \oplus \hat{X}_i | \hat{X}) \\ &= H(X) - H(Z) \\ &= H_b(p) - H_b(D). \end{aligned}$$

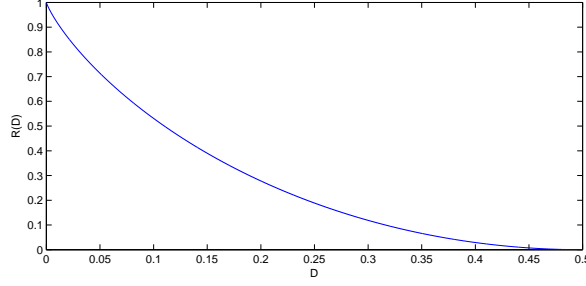


Fig. 2. Rate distortion function for a Bernoulli ($\frac{1}{2}$) source.

Theorem 2 (The rate distortion function for a $\mathcal{N}(0, \sigma^2)$ source with squared-error distortion)

$$R(D) = \begin{cases} \frac{1}{2} \log \frac{\sigma^2}{D} & 0 \leq D \leq \sigma^2 \\ 0 & D \geq \sigma^2 \end{cases}$$

Proof : Let X be $\sim \mathcal{N}(0, \sigma^2)$. By the rate distortion theorem extended to continuous alphabets, we have

$$R(D) = \min_{f(\hat{x}|x): E(\hat{X} - X)^2 \leq D} I(X; \hat{X}). \quad (7)$$

First we should find the lower bound for the rate distortion function and prove that this is achievable.

$$\begin{aligned} I(X; \hat{X}) &= h(X) - h(X|\hat{X}) \\ &= \frac{1}{2} \log(2\pi\epsilon)\sigma^2 - h(X - \hat{X}|\hat{X}) \\ &\geq \frac{1}{2} \log(2\pi\epsilon)\sigma^2 - h(X - \hat{X}) \\ &\geq \frac{1}{2} \log(2\pi\epsilon)\sigma^2 - h(\mathcal{N}(0, E(X - \hat{X})^2)) \\ &= \frac{1}{2} \log(2\pi\epsilon)\sigma^2 - \frac{1}{2} \log(2\pi\epsilon)E(X - \hat{X})^2 \\ &\geq \frac{1}{2} \log(2\pi\epsilon)\sigma^2 - \frac{1}{2} \log(2\pi\epsilon)D \\ &= \frac{1}{2} \log \frac{\sigma^2}{D} \end{aligned}$$

Conclusion:

$$R(D) \geq \frac{1}{2} \log \frac{\sigma^2}{D} \quad (8)$$

If $D \leq \sigma^2$ we choose

$$X = \hat{X} + Z, \hat{X} \sim \mathcal{N}(0, \sigma^2 - D), Z \sim \mathcal{N}(0, D)$$

where \hat{X} and Z are independent. For this joint distribution, we calculate

$$I(X; \hat{X}) = \frac{1}{2} \log \frac{\sigma^2}{D} \quad (9)$$

and $E(X - \hat{X})^2 = D$, thus achieving the bound. If $D > \sigma^2$, we choose $\hat{X} = 0$ with probability 1, achieving $R(D) = 0$. Hence, the rate distortion function for the Gaussian source with squared-error distortion is

$$R(D) = \begin{cases} \frac{1}{2} \log \frac{\sigma^2}{D} & 0 \leq D \leq \sigma^2 \\ 0 & D \geq \sigma^2 \end{cases}$$

We can rewrite $R(D)$ as $D(R) : D(R) = \sigma^2 2^{-2R}$.

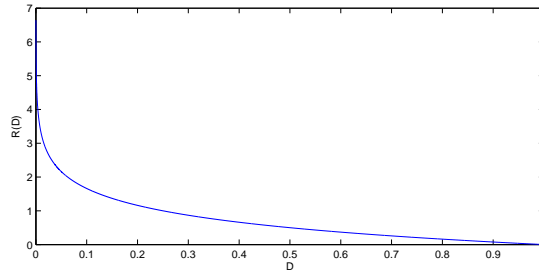


Fig. 3. Rate distortion function for a Gaussian source.

II. STRONG TYPICALITY SET

We define Weak Typicality set as: (*Weak typicality*)

$$A_\epsilon^{(n)} = \left\{ x^n \in \mathcal{X}^n : \left| -\frac{1}{n} \log P(x^n) - H(X) \right| \leq \epsilon \right\}. \quad (10)$$

The expression $N(a|X^n)$ is defined as the number of appearances of symbol a in the sequence X^n

Example: $X^n = 01011110 \Rightarrow N(0|X^n) = 3, N(1|X^n) = 5$

Definition 8 (*Strong Typicality*) A sequence $x^n \in \mathcal{X}^n$ is said to be ϵ – *strongly typical* with respect to a distribution $P(x)$ on \mathcal{X} if:

- For all $a \in \mathcal{X}$ with $P_X(a) > 0$, we have:

$$\left| \frac{N(a|X^n)}{n} - P_X(a) \right| \leq \frac{\epsilon}{|\mathcal{X}|} \quad (11)$$

- For all $a \in \mathcal{X}$ with $P_X(a) = 0$, $N(a|X^n) = 0$.

Lemma 1 For $X \sim i.i.d.$ and the expression : $\frac{N(a|X^n)}{n}$ if we take $n \rightarrow \infty$ then we get:

$$\frac{N(a|X^n)}{n} \rightarrow P_X(a)$$

Proof:

$$N(a|X^n) = \sum_{i=1}^n 1_a(x_i) \quad (12)$$

$$1_a(X_i) = \begin{cases} 1 & X_i = a \\ 0 & X_i \neq a \end{cases} \quad (13)$$

By the Law of large numbers , for any $\delta \geq 0$, $\epsilon > 0 \exists n$ s.t

$$\Pr \left(\left| \frac{N(a|X^n)}{n} - P_X(a) \right| < \epsilon \right) \geq 1 - \delta$$

Theorem 3 The typical set A_ϵ^n has the following properties

1) If $x^n \in A_\epsilon^{(n)}(x)$ then:

$$H(X) - \epsilon_1 \leq -\frac{1}{n} \log P(x^n) \leq H(X) + \epsilon_1 \quad (14)$$

2) For all $\delta \geq 0$ exists n sufficiently large s.t $\Pr(X^n \in T_\epsilon^{(n)}(x)) \geq 1 - \delta$

3) $2^{n(H(x)-\epsilon_2)} \leq |T_\epsilon^{(n)}(x)| \leq 2^{n(H(x)+\epsilon_2)}$

Proof (1):

$$\begin{aligned}
 -\frac{1}{n} \log P_x(X^n) &\stackrel{X \sim i.i.d}{=} -\frac{1}{n} \log \prod_{i=1}^n P_x(X^n) \\
 &= -\frac{1}{n} \sum_{i=1}^n \log P_x(X^n) \\
 &= -\frac{1}{n} \sum_{a \in \mathcal{X}} N(a|X^n) \log P_x(X^n)
 \end{aligned}$$

Example 3 For the series $X^n = 0001011$ with probabilities: $p(0) = \frac{1}{4}, p(1) = \frac{3}{4}$

$$N(0|X^n) = 4, N(1|X^n) = 3$$

Instead of summing $\log \frac{1}{4} + \log \frac{1}{4} + \log \frac{1}{4} + \log \frac{3}{4} + \log \frac{3}{4} + \log \frac{3}{4} + \dots$

We will multiply the number of zeroes and ones in the the corresponded entropy

$$\begin{aligned}
 N(0|X^n) \log \frac{1}{4} + N(1|X^n) \log \frac{3}{4} &= \left| -H(X) - \frac{1}{n} \log P_x(X^n) \right| \\
 &= \left| \sum_{a \in \mathcal{X}} P_x(a) \log P_x(a) - \frac{1}{n} \log P_x(X^n) \right| \\
 &= \left| \sum_{a \in \mathcal{X}} \left(P_x(a) - \frac{N(a|X^n)}{n} \right) - \log P_x(a) \right| \\
 &\leq \frac{\epsilon}{|X|} \sum_{a \in \mathcal{X}} |\log P_x(a)| = \epsilon_1
 \end{aligned}$$

Definition 9 (*Joint Typical Set*)

$$T_\epsilon^{(n)}(X, Y) = \left\{ X^n, Y^n : \left| \frac{N(a, b|X^n, Y^n)}{n} - P_{xy}(a, b) \right| \leq \frac{\epsilon}{|X||Y|} \right\} \quad (15)$$

If $P_{x,y}(a, b) = 0, N(a, b|X^n, Y^n) = 0$

Definition 10 (*Conditional strongly typical set*)

Let $Y^n \in T_\epsilon^{(n)}(Y)$ then:

$$T(X|Y^n) = \{X^n : (X^n, Y^n) \in T_\epsilon^{(n)}(X, Y)\} \quad (16)$$

$$|T(X|Y^n)| = 2^{nH(X|Y)}$$

$$T(Y|X^n) = \{Y^n : (Y^n, X^n) \in T_\epsilon^{(n)}(X, Y)\} \quad (17)$$

$$|T(Y|X^n)| = 2^{nH(Y|X)}$$

$$|T_\epsilon^{(n)}(X, Y)| = 2^{nH(Y, X)} |T_\epsilon^{(n)}(X|Y)| = 2^{nH(X|Y)} \quad (18)$$