

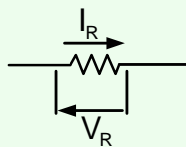
## Current Sensing

- 9.1 Resistor
- 9.2 Current transformer

## Current Sensing

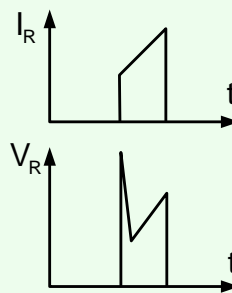
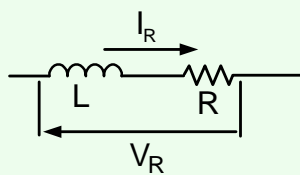
- \* Control PCM, ACM
- \* Protection

Sense Resistor



Problems

- \* Inductive component



## Losses

$$P_d = R I_{Rms}^2 = V_{Rms} I_{Rms}$$

For a reasonable  $S/N$   $V_R \approx 100\text{mV}$  at least

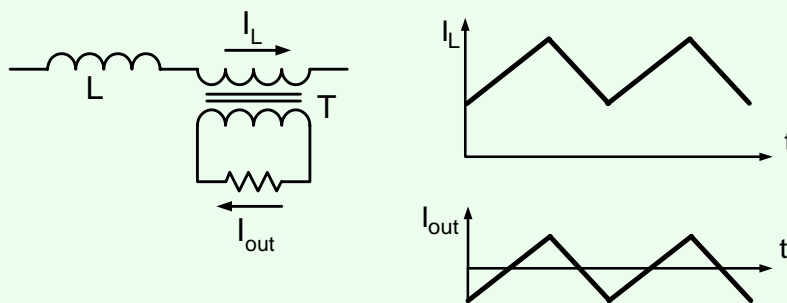
Assuming  $V_R, V_{Rms}$  same order of magnitude

$$P_d \approx 0.1 I_{Rms}$$

$$I_{rms} = 10 \text{ A} \quad P_d \cong 1 \text{ W}$$

Not practical for  $I > 10\text{A}$

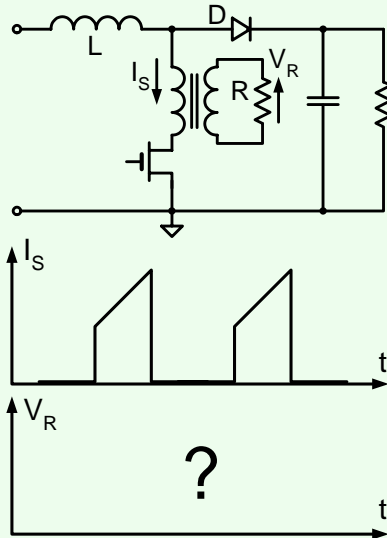
## Current transformer



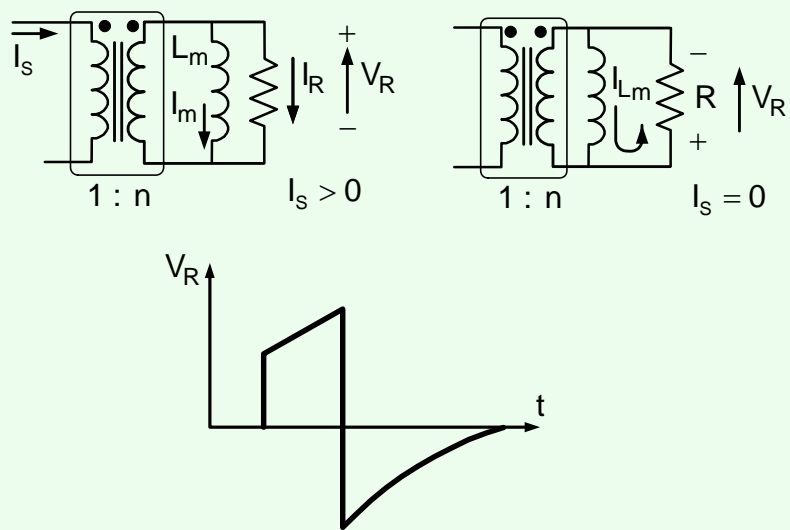
DC component via primary lost !

DC component may saturate transformer !

### Current Transformer



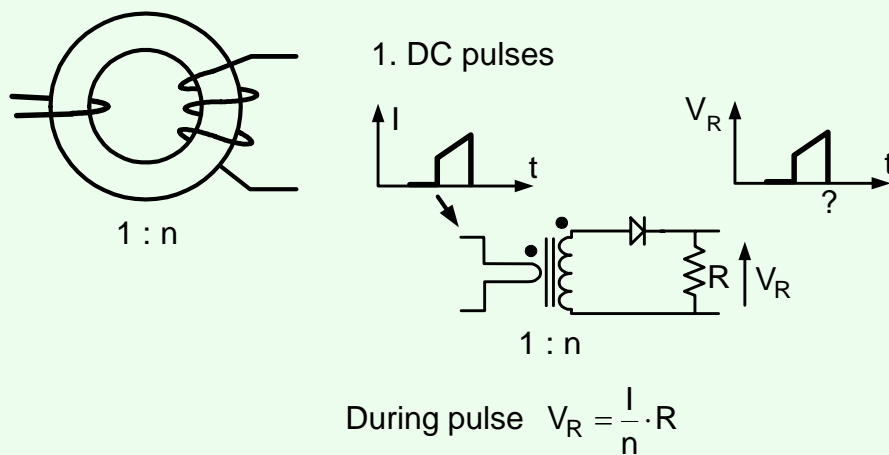
### Current Transformer



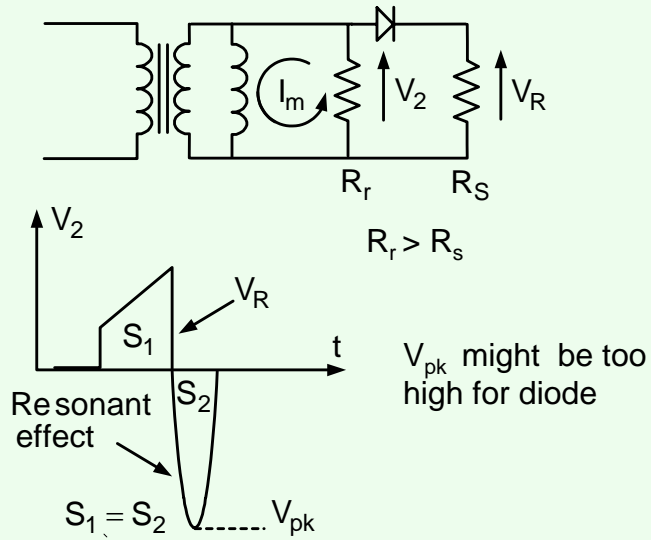
## Conclusions

- Linear Current transformers are useful only if current to be measured is AC
- In Power Electronics, Pulse Current transformer is useful for measuring pulsed current

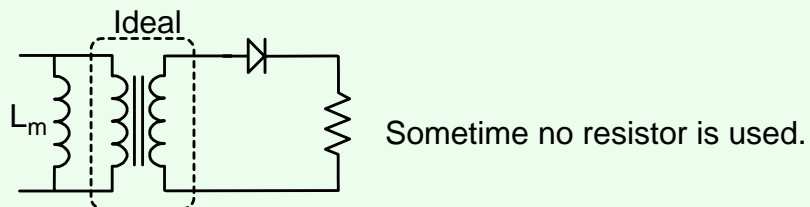
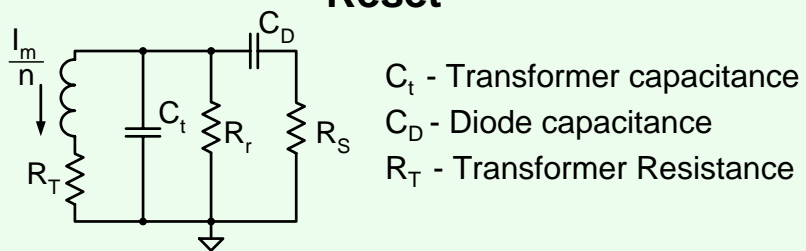
## Pulse Current transformer Design



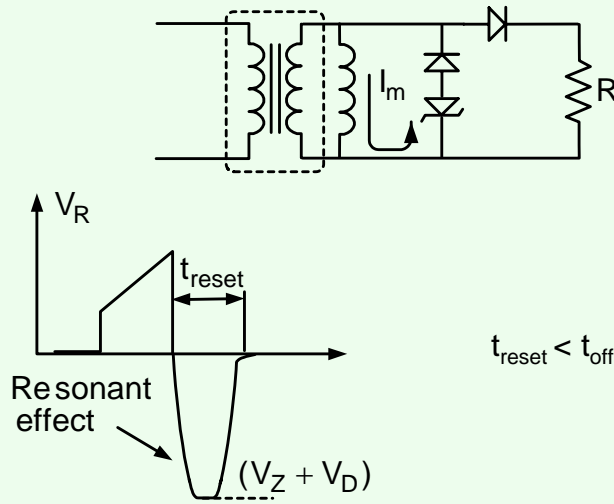
### Resistor reset



### Reset

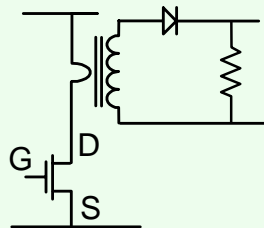


### Reset - Clamp

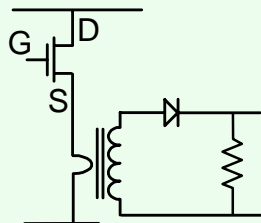


### Place to put current transformer

O.K.



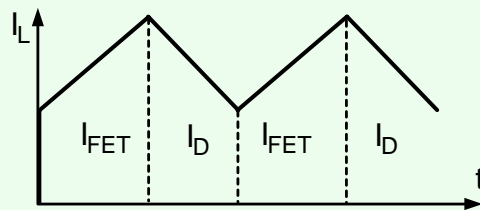
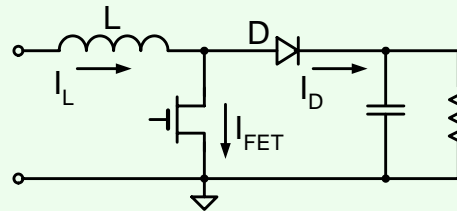
avoid



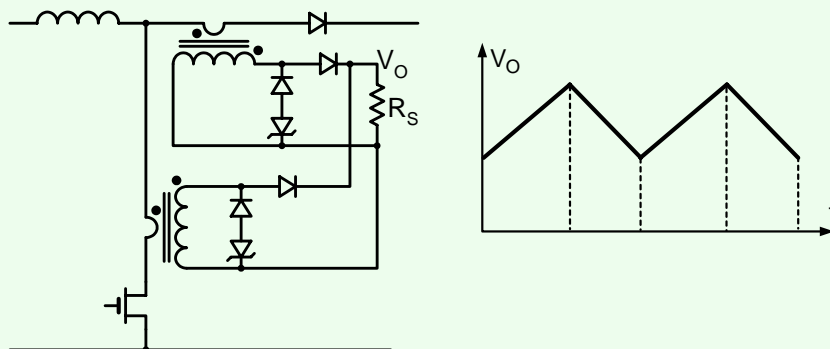
Why ?

## Measuring "DC" current with pulse current transformer

Need to measure  $I_L$      $I_L = I_D + I_{FET}$

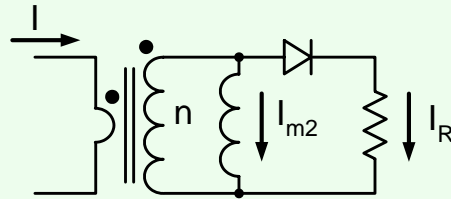


## Inductor DC Current



Long wire for illustration only

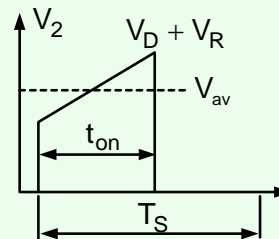
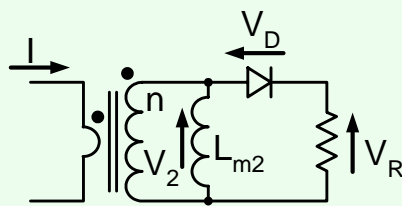
### Problem



$$\frac{I}{n} = I_{m2} + I_R$$

$I_{m2}$  must be smaller than  $I_R$  or  $2\pi f_s L_m > R$   
 This becomes a problem at low frequencies

### Design of current transformer



Transformer operation is limited by voltage NOT CURRENT

$$B_{max} = \frac{\int V dt}{n A_e} \quad V_R \cong \frac{I}{n} R$$

$$B_{max} = \frac{I_{av} R D_{max}}{n A_e f_s}$$

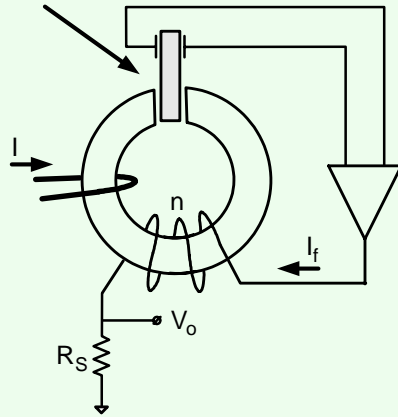
$$\int V dt = V_{av} t_{on} = \frac{V_{av} D_{on}}{f_s}$$

If  $I_{av}$  large need R small.  
 Problem at low frequencies



## DC Current transformer

Active Device  
Hall effect sensor



Null operation  $\Phi=0$   
by feedback

$$I_f \cdot n = I \quad V_o = \frac{I}{n} R_s$$