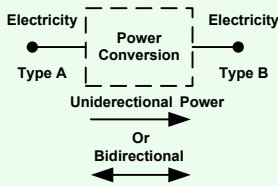


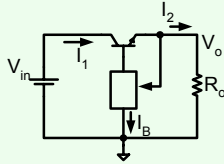
The problem of Power Conversion



- AC-DC Rectifier
- DC-DC Power converter
- DC-AC Inverter
- AC-AC Cycloconverter

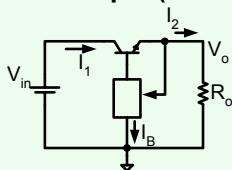
This course will concentrate on DC-DC converters

Linear Regulator



- $I_B \rightarrow$ Small
- $I_1 \approx I_2$
- Power lost depends on voltage drop on regulator
- Regulator needs a minimum of 3 volts
- Low Drop Regulators $\sim \min(V_{in}-V_o)=1V$
- But: $V_{in}-V_o$ Variations $\sim 3V$

Example (Cont.)



100W, 5V power supply

Assume:

$(V_{in} - V_o)_{nominal} \approx 3V$

$(V_{in} - V_o)_{max} \approx 5V$

$$\frac{P_{loss}}{P_o} = \frac{5V}{5V} = 1; \rightarrow P_{loss} = 100W$$

$$\eta\% = \frac{100}{200} \cdot 100 \approx 50\%$$

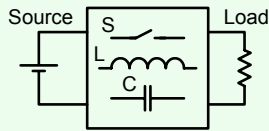
Example (Cont.)

The problem is not $\eta\% = 50\%$ It is **100W!**

- Battery -> efficiency
- Line operation -> heat dissipation
- Cooling -> size, expense

Modern Power Conversion Systems Requirements

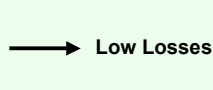
- High efficiency
- Small size
- Cost



L, C: Reactive elements

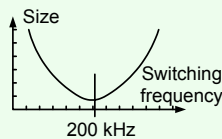
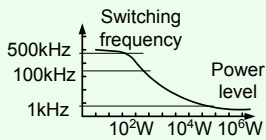
S: "On" Resistance $\rightarrow 0$

"Off" Resistance $\rightarrow \infty$



Disadvantages

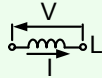
- More Expensive (in general)
- Noisy
- Less Reliable
- Switching Losses



PWM

Inductor_1

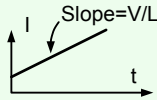
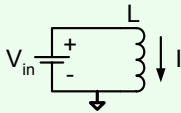
$$\frac{di}{dt} = \frac{V}{L}$$



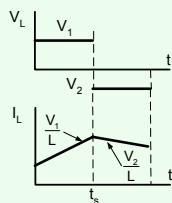
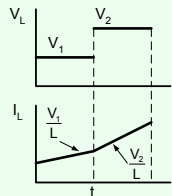
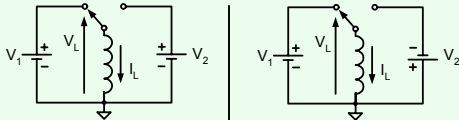
In most Power Electronics cases $V = \text{constant}$ over time period of interest

$$\frac{\Delta i}{\Delta t} = \frac{V}{L};$$

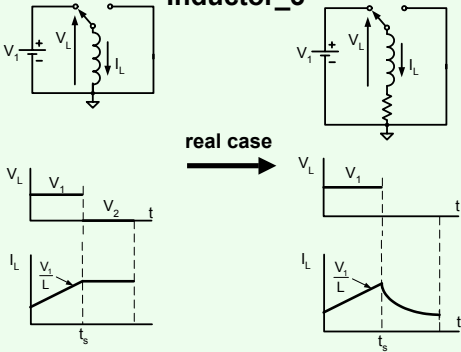
$$\Delta i = \frac{V}{L} \Delta t;$$



Inductor_2



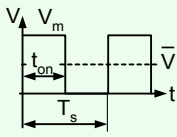
Inductor_3



Average Signals

Most important equation in Power Electronics: $\frac{dI}{dt} = \frac{V}{L}$

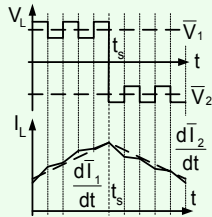
Correct for average too: $\frac{d\bar{I}}{dt} = \frac{\bar{V}}{L}$



$$\bar{X} = \frac{1}{T} \int_0^T X dt$$

\bar{X} - average

$$\bar{V} = \frac{V_m \cdot t_{on}}{T_s} = V_m D_{on}$$



Implication

For any practical system in steady state:

Average voltage on inductor $\bar{V}_L = 0$

Proof:

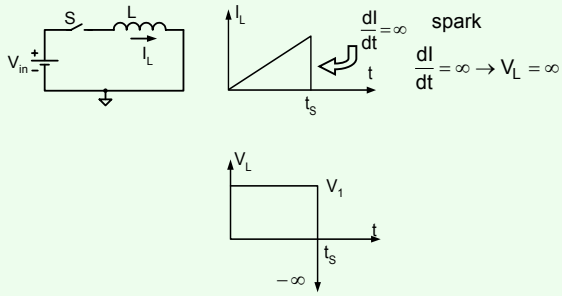
If $\bar{V}_L \neq 0$ then $\bar{I}_L \rightarrow \infty$

That is:

System must be designed such that:

$$\bar{V}_L = 0$$

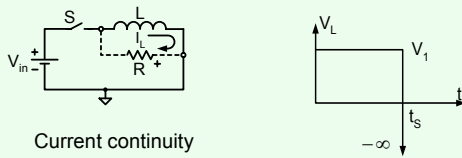
Inductor current interruption



Inductor current interruption

What is the polarity?

The imaginary resistor method



Current continuity
