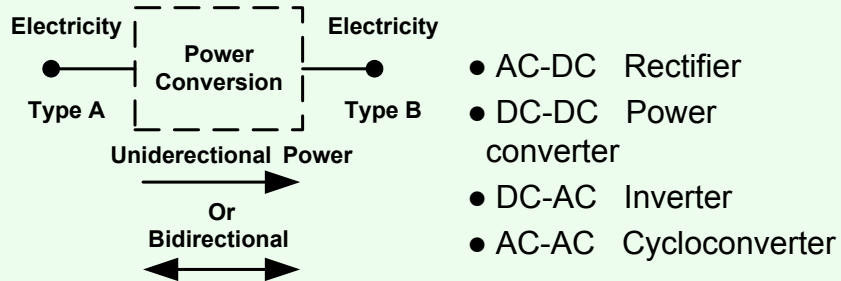
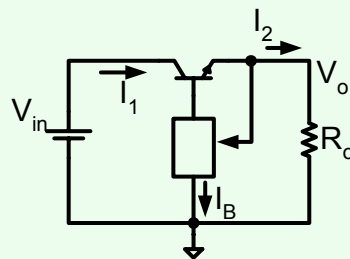


## The problem of Power Conversion



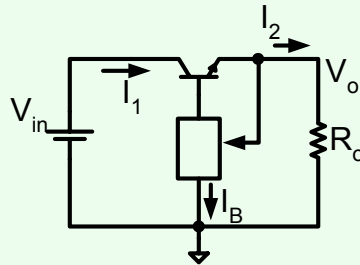
This course will concentrate on DC-DC converters

## Linear Regulator



- $I_B \rightarrow$  Small
- $I_1 \approx I_2$
- Power lost depends on voltage drop on regulator
- Regulator needs a minimum of 3 volts
- Low Drop Regulators  $\sim \min(V_{in} - V_o) = 1V$
- But:  $V_{in} - V_o$  Variations  $\sim 3V$

## Example (Cont.)



100W, 5V power supply

Assume:

$$(V_{in} - V_o)_{nominal} \approx 3V$$

$$(V_{in} - V_o)_{max} \cong 5V$$

$$\frac{P_{loss}}{P_o} = \frac{5V}{5V} = 1; \rightarrow P_{loss} = 100W$$

$$\eta\% = \frac{100}{200} \cdot 100 \approx 50\%$$

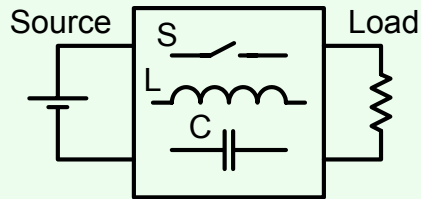
## Example (Cont.)

The problem is not  $\eta\% = 50\%$  **It is 100W !**

- Battery -> efficiency
- Line operation -> heat dissipation
- Cooling -> size, expense

## Modern Power Conversion Systems Requirements

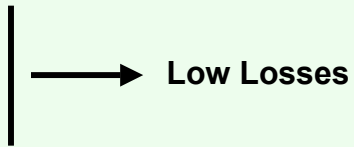
- High efficiency
- Small size
- Cost



L, C: Reactive elements

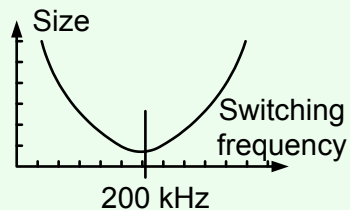
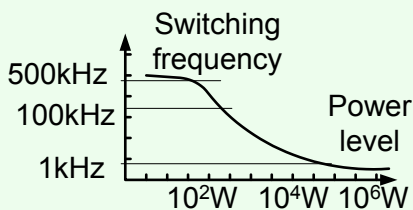
S: "On" Resistance  $\rightarrow 0$

"Off" Resistance  $\rightarrow \infty$



## Disadvantages

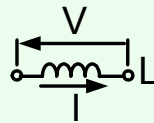
- More Expensive (in general)
- Noisy
- Less Reliable
- Switching Losses



# PWM

## Inductor\_1

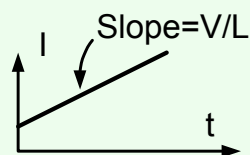
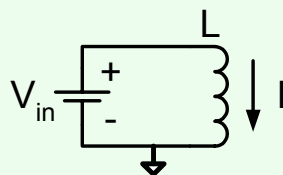
$$\frac{di}{dt} = \frac{V}{L}$$



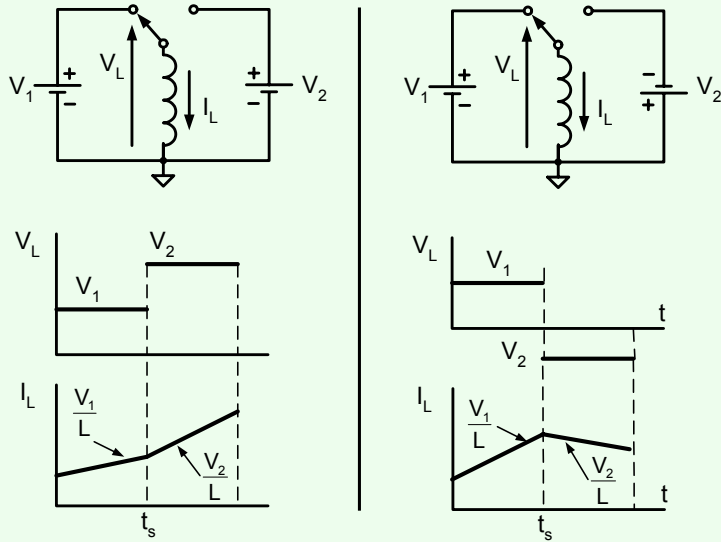
In most Power Electronics cases  $V = \text{constant}$  over time period of interest

$$\frac{\Delta i}{\Delta t} = \frac{V}{L};$$

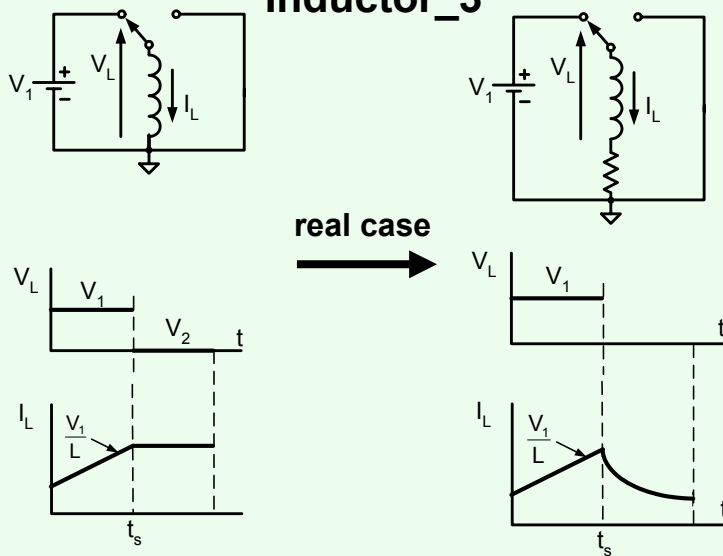
$$\Delta i = \frac{V}{L} \Delta t;$$



### Inductor\_2



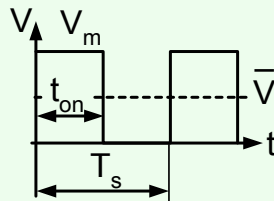
### Inductor\_3



## Average Signals

Most important equation in Power Electronics:  $\frac{di}{dt} = \frac{V}{L}$

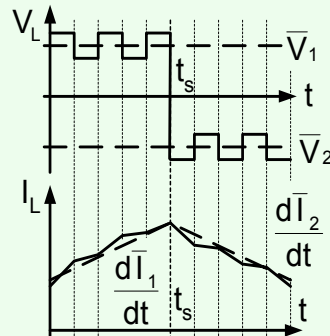
Correct for average too:  $\frac{d\bar{i}}{dt} = \frac{\bar{V}}{L}$



$$\bar{X} = \frac{1}{T} \int_0^T X dt$$

$\bar{X}$  - average

$$\bar{V} = \frac{V_m \cdot t_{on}}{T_s} = V_m D_{on}$$



## Implication

For any practical system in steady state:

Average voltage on inductor  $\bar{V}_L = 0$

Proof:

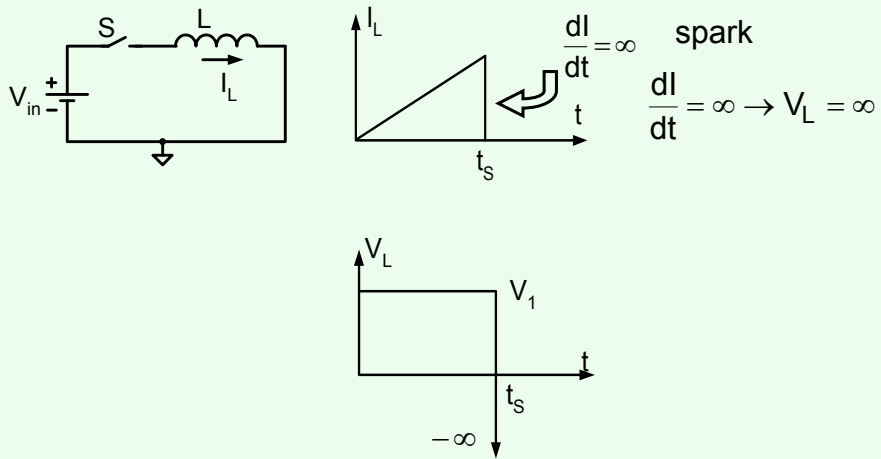
If  $\bar{V}_L \neq 0$  then  $\bar{I}_L \rightarrow \infty$

That is:

System must be designed such that:

$$\bar{V}_L = 0$$

## Inductor current interruption



## Inductor current interruption

### What is the polarity?

The imaginary resistor method

