



where  $\hat{x} = (x_1 + x_2)/2$ ,  $\hat{y} = (y_1 + y_2)/2$ ,  $\Delta x = x_1 - x_2$ , and  $\Delta y = y_1 - y_2$ .

At first glance we note a few properties of this mutual intensity. First, it contains information about the depth dimension of the source through the variable  $z_s$  in the exponent. Second, the modules of  $J$ , in general, are space variant because of the dependence on  $\hat{x}$  and  $\hat{y}$ . Finally, although  $J$  is space variant, the intensity distribution is uniform over the observation plane as in the case of a planar incoherent source.<sup>6</sup> The far-field intensity distribution is given by

$$I(x, y) = J(\Delta x = 0, \Delta y = 0) = C \int I_s(\mathbf{r}_s) d^3 r_s \equiv I_0. \quad (3)$$

We conclude that, in general, the modules of the mutual intensity induced by a 3-D incoherent source are space variant in a special way, depending on the product of the center of gravity of the measurement points ( $\hat{x}$ ,  $\hat{y}$ ) and the distance between them ( $\Delta x$ ,  $\Delta y$ ); i.e.,

$$|J(x_1, y_1, x_2, y_2)| = |J(\Delta x, \Delta y, \hat{x}\Delta x, \hat{y}\Delta y)|.$$

By considering specific points on the  $x$ - $y$  plane, we reduce the four-dimensional mutual intensity given by Eq. (2) to a 3-D function. The desired points are all the pairs situated simultaneously on a radial line emanating from the origin. Formally, this restriction satisfies the condition  $x_1 y_2 = x_2 y_1$ . If we use the relation  $\hat{r}\Delta r = \hat{x}\Delta x + \hat{y}\Delta y$ , the mutual intensity appears now in the general form of  $J(x_1, y_1, x_2, y_2) = J(\Delta x, \Delta y, \hat{r}\Delta r)$ , where  $\hat{r} = \sqrt{\hat{x}^2 + \hat{y}^2}$  and  $\Delta r = \sqrt{\Delta x^2 + \Delta y^2}$ . Measuring the degree of coherence along these special points enables us to reconstruct (by a 3-D inverse Fourier transform) the 3-D intensity distribution of the source as seen from the observation plane. To see that, let us change the variable  $\hat{r}$  to  $q = \hat{r}\Delta r/\Delta r_{\min}$ . Substituting the new variable into Eq. (2) and normalizing  $J$  yield the following complex degree of coherence:

$$\begin{aligned} \mu(\Delta x, \Delta y, q) &\equiv \frac{J(\Delta x, \Delta y, \hat{r}\Delta r)}{I(x, y)} \\ &= C_0 \int I_s(\mathbf{r}_s) \exp \left[ \frac{-j2\pi}{\lambda} \left( \frac{x_s \Delta x + y_s \Delta y}{R} \right. \right. \\ &\quad \left. \left. + \frac{z_s q \Delta r_{\min}}{R^2} \right) \right] d^3 r_s, \end{aligned} \quad (4)$$

where  $C_0 = I_0^{-1} \exp(jkq\Delta r_{\min}/R)$ . Equation (4) indicates that the degree of coherence along the coordinates  $(\Delta x, \Delta y, q)$  is a 3-D Fourier transform (with scaling factors) of the source's 3-D intensity distribution, as seen from the far paraxial zone.

The experimental system is shown in Fig. 2. As mentioned above, we have reduced the system's dimensions to one transverse coordinate only for simplicity, realizing that the new physics (i.e., the relation between the far-field coherence and the source's depth distribution) is demonstrated as well in the reduced

system. For this system Eq. (4) naturally becomes

$$\begin{aligned} \mu(\Delta x, p) &= I_0^{-1} \exp(jKp\Delta k_{\min}/R) \\ &\times \iint I_s(x_s, z_s) \exp \left[ \frac{-j2\pi}{\lambda} \left( \frac{x_s \Delta x}{R} \right. \right. \\ &\quad \left. \left. + \frac{z_s p \Delta x_{\min}}{R^2} \right) \right] dx_s dz_s, \end{aligned} \quad (5)$$

where the variable  $\hat{x}$  is replaced by  $p = \hat{x}\Delta x/\Delta x_{\min}$ . The source's intensity distribution is reconstructed from the 2-D inverse Fourier transform of the measured degree of coherence, i.e.,

$$I_s(x_s, z_s) \propto \text{IFT}_{2-D} \left[ \mu \left( \frac{\Delta x}{\lambda R}, \frac{p \Delta x_{\min}}{\lambda R^2} \right) \right], \quad (6)$$

where  $\text{IFT}_{2-D}$  indicates a 2-D inverse Fourier transform. Equation (6) describes the reconstruction procedure of the source from the measured data.

The incoherent source in the following experiment is a two-point object produced by rotating a diffuser in front of two laser beams. Because of the different distance of each point source to the detection setup, the points are distributed in the  $(x_s, z_s)$  plane (see Fig. 2). The changeable pinholes are made by two slits tilted toward each other. Along each line parallel to the  $x$  axis there are effectively two pinholes with different distances between them. We change the pinholes' center of gravity by moving the slits together in parallel to the  $x$  axis. For each slit's location  $\hat{x}$ , a set of interference gratings, each for a different  $\Delta x$ , is obtained in the back focal plane of the cylindrical lens. The experiment's parameters are  $\lambda = 0.63 \mu\text{m}$ ,  $R = 71 \text{ cm}$ ,  $\hat{x}_{\max} = 9.5 \text{ mm}$ ,  $\Delta x = 0.2\text{--}0.6 \text{ mm}$ ,  $\Delta z_s = 9 \text{ cm}$ , and  $\Delta x_s \sim 2 \text{ mm}$ .

Sixty-four sets of interference gratings, five gratings in each, were measured. Each of the sets was obtained for a different pinhole's center of gravity  $\hat{x}$ . The visibility and the phase of each grating were measured and collected into the computer's memory. The complex visibility obtained from five gratings (five distances  $\Delta x$  between the pinholes) in sixty-four different centers of gravity is shown in Figs. 3(a) and 3(b). Note that the frequency of the visibility function along  $\hat{x}$  increases

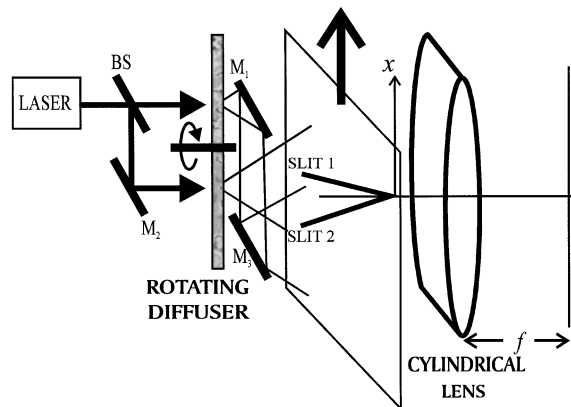


Fig. 2. Experimental setup: BS, beam splitter; M's, mirrors.

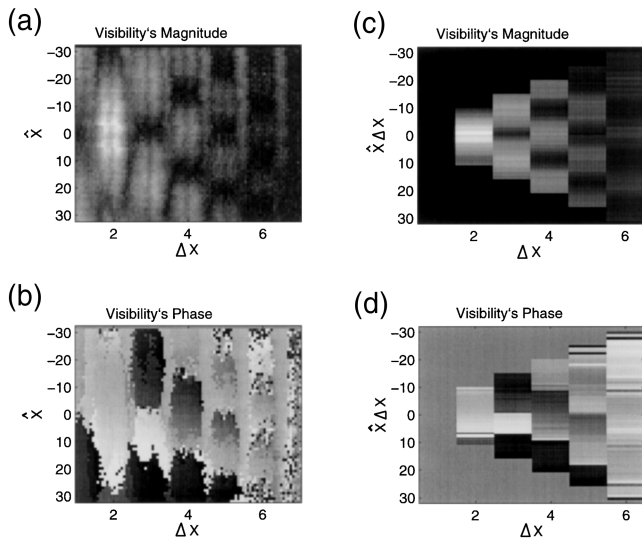


Fig. 3. (a) Magnitude and (b) phase of the degree of coherence as a function of  $(\Delta x, \hat{x})$ . (c), (d) Same as (a) and (b) after transformation of the coordinates to  $(\Delta x, \hat{x}\Delta x/\Delta x_{\max})$ .

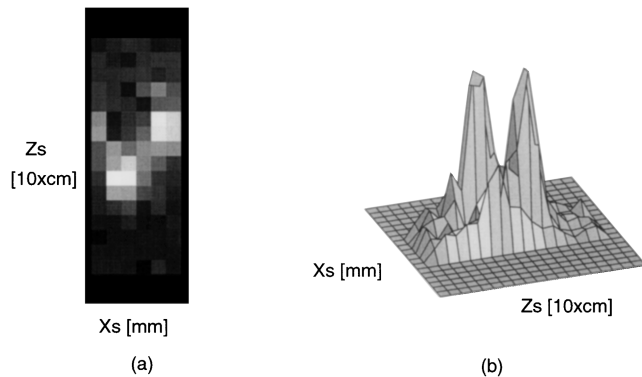


Fig. 4. Reconstruction of the source by an inverse Fourier transform of the complex function shown in Figs. 3(c) and 3(d). (a) Gray-level image, (b) 3-D plot.

linearly with  $\Delta x$  and that the distance between any two peaks of brightness, in each  $m$ th column [see Fig. 3(a)], follows the relation  $\lambda R^2/\Delta z_s \Delta x_m \cong 3.53 m^{-1} \text{ cm}$ ,  $m = 2, \dots, 6$ , as indeed expected from Eq. (5)

To reconstruct the source shape from the sampled complex visibility one first needs to transform the measured data to the coordinates  $(\Delta x, p)$ . To gain more longitudinal resolution it is worth changing the coordi-

nates  $(\Delta x, \hat{x})$  to  $(\Delta x, \hat{x}\Delta x/\Delta x_{\max})$ . The minimum object depth that can be resolved now is  $\lambda R^2/\hat{x}_{\max}\Delta x_{\max}$  instead of  $\lambda R^2/\hat{x}_{\max}\Delta x_{\min}$ , as results from Eq. (5). As a result of this transformation the visibility plane is not completely occupied with measured data. Zero values are filled in the entire area of missing data, as is shown in Figs. 3(c) and 3(d).

The reconstruction of the source shape, shown in Fig. 4, was obtained by a 2-D inverse Fourier transformation of the complex visibility shown in Figs. 3(c) and 3(d). The zero padded areas in Figs. 3(c) and 3(d) can be considered a bandpass filtering and explain the noise that surrounds the two bright points in Fig. 4. One can extrapolate the visibility function into the zero padded areas and thus reduce the degradation in the reconstructed image. However, this subject is beyond the scope of the present preliminary demonstration.

In conclusion, a new kind of space-variant degree of coherence was experimentally demonstrated. This degree of coherence was obtained in the far field of an incoherent source distributed along the longitudinal axis. We demonstrated a reconstruction of an axially distributed source from this degree of coherence, measured by a Young-experiment setup. The experimental results confirm the theory developed in Refs. 2 and 3. Extending the system to three dimensions promises a new method of incoherent holography and 3-D imaging.

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