

# Analysis and Design of a Piezoelectric Transformer AC/DC Converter in a Low Voltage Application

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**Abstract** - steady-state processes in a power PT converter with a half-way two diodes output rectifier are studied. It is shown that such a power converter can operate in two modes: with or without overlap of the conduction intervals of the diodes. The analytical equations and characteristics derived in this study were found to be in good agreement with simulation and experimental results. The study highlights the effect of the load and parasitic resistances on the output voltage and the losses for both modes. Expressions obtained in the paper can be used in engineering designs.

## I. INTRODUCTION

Piezoelectric Transformers (PT) convert electric power into electric power via a mechanical resonant link. PT's have important advantages over magnetic transformers in a few applications that require a low DC output voltage [1-6]. In this case a half-way output rectifier with two diodes is the preferred choice. However, in earlier investigations only one operational mode of this rectifier was studied: when the conducting intervals of both diodes of the rectifier do not overlap. The presented paper shows that this operation mode is not unique. In a wide range of load resistances the rectifier operates in another mode in which the conduction intervals of the diodes overlap. The paper presents a generalized detailed analysis of both operating modes. The results of this analysis reveal new important characteristics of this rectification scheme.

## II. PRINCIPLE OF OPERATION OF THE HALF-WAY TWO DIODES RECTIFIER

The conventional equivalent circuit of the PT was used to analyze the low voltage AC/DC converter topology (Fig. 1). It includes  $L_r, C_r, R_m, C_{in}, C_o$ , a voltage source

$\frac{v_{Co}}{n}$  and a current source  $\frac{i_r}{n}$  ( $n$  is the transformer turn ratio) [7]. A half-way rectifier Rect and an inductor  $L_o$  are connected at the output of the PT. The rectifier includes two diodes ( $D_1, D_2$ ) and  $L_f, C_f$  filter.  $R_L$  is the load resistance. The function of  $L_o$  in this circuit is to provide a path for the DC current and also to cancel the circulating energy caused by  $C_o$  [2]. The resonant frequency of the parallel circuit  $L_o, C_o$  has to be equal to the series resonant frequency of the PT.

The simulated current and voltage waveforms of the rectifier operating in overlapping and non-overlapping modes are given at Fig. 2 a, b ( $\vartheta = \omega t$  is the normalized time,  $\omega$  is the operating angle frequency). The PT current  $i_r$  is assumed to be sinusoidal in both modes due to the high  $Q$  of practical PTs. The capacitor  $C_o$  voltage is practically sinusoidal in the non-overlapping mode but has a discontinuous nature (intervals of zero voltage) in the overlapping mode. We study here in detail the overlapping mode.

During the interval  $\vartheta_1 \vartheta_2 = \lambda$  the voltage  $v_{Co}$  across the capacitor  $C_o$  is positive, therefore the diode  $D_1$  is ON and the diode  $D_2$  – OFF. At  $\vartheta_2$ , the polarity of the voltage  $v_{Co}$  changes and therefore  $D_2$  turns on. If just before  $\vartheta_2$ , the instant current of  $D_1$  ( $i_{D1}$ ) is higher than the absolute value of the capacitor  $C_o$  current ( $i_{Co}$ ) the rectifier will operate under overlapping conditions.

In this case the diodes  $D_1$  and  $D_2$  are conducting simultaneously during the interval  $\vartheta_2 \vartheta_3$ , the current  $i_{D2}$  is increasing while the current  $i_{D1}$  is decreasing (due to changing  $i_r$ ).

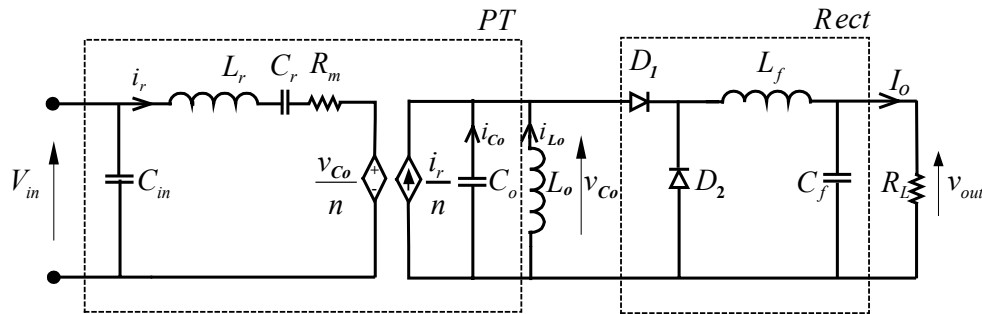


Fig. 1. The PT converter loaded by a half-way two diodes rectifier.

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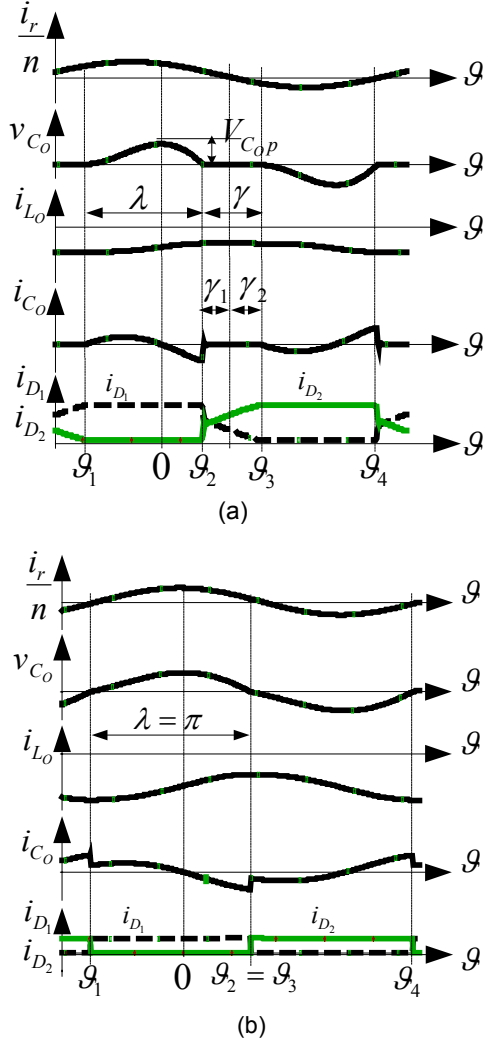


Fig. 2. The rectifier's current and voltage waveforms in the overlapping (a) and non-overlapping (b) modes.

During this overlapping interval, the current  $i_{C_0}=0$ , because diodes short the capacitor. At  $\vartheta_3$ ,  $i_{D1}=0$  and  $D_1$  turns off. During  $\vartheta_3\vartheta_4$ , only  $D_2$  is ON and  $v_{C_0} < 0$ . Inductance  $L_o$  charges by the input supply and its current increases. At  $\vartheta_4$ ,  $v_{C_0}$  changes polarity and an overlapping interval begins again, but now  $i_{D1}$  is increasing while  $i_{D2}$  is decreasing, etc.

### III. THE UNIFIED ANALYSIS OF THE OVERLAPPING AND NON-OVERLAPPING MODES

Analysis is carried out under the following assumptions:

- Diodes and reactive elements are ideal;
- The output filter is ideal ( $L_r = \infty$ ,  $C_r = \infty$ );
- The current  $i_r$  has a sinusoidal waveform.
- The operation frequency  $\omega$  is equal to the resonant frequency:  $\omega = \frac{1}{\sqrt{L_r C_r}} = \frac{1}{\sqrt{L_o C_o}}$ .

#### A. Lossless PT ( $R_m=0$ )

We assume that the impulses of  $v_{C_0}$  have a sinusoidal shape and that the duration of each impulse is approximately  $\lambda$  (Fig. 2). According to this assumption:

$$v_{C_0}(\vartheta) = V_{C_{OP}} \cos\left(\frac{\pi}{\lambda} \vartheta\right) \quad (1)$$

where  $V_{C_{OP}}$  is the peak of the voltage across the capacitor  $C_o$ .

The peak of the first harmonic of this voltage:

$$V_{C_{O(1)p}} = \frac{4}{\lambda} V_{C_{OP}} \frac{\cos\left(\frac{\lambda}{2}\right)}{\left(\frac{\pi}{\lambda}\right)^2 - 1} \quad (2)$$

The average output voltage  $V_{out}$  is equal to the DC component of the positive value of  $v_{C_0}$ :

$$V_{out} = V_{C_{OP}} \frac{\lambda}{\pi^2} \quad (3)$$

Combining (3) in (2) we obtain:

$$V_{C_{O(1)p}} = 4V_{out} \frac{\cos\left(\frac{\lambda}{2}\right)}{1 - \left(\frac{\lambda}{\pi}\right)^2} \quad (4)$$

Since the operating frequency is equal to the resonant frequency of the series circuit  $C_r, L_r$ :

$$\frac{V_{C_{O(1)p}}}{n} = V_{in,p} \quad (5)$$

The transfer ratio of the output voltage of the rectifier  $V_{out}$  to the peak of the input voltage  $V_{in,p}$  for the ideal PT is:

$$k_{o_{ideal}} = \frac{V_{out}}{nV_{in,p}} = \frac{1 - \left(\frac{\lambda}{\pi}\right)^2}{4 \cos\left(\frac{\lambda}{2}\right)} \quad (6)$$

In the non-overlapping mode:

$$k_{o_{ideal}}^{NOM} = \lim_{\lambda \rightarrow \pi} (k_{o_{ideal}}) = \frac{1}{\pi} \quad (7)$$

At the instant  $\vartheta_2$  the diode  $D_2$  carries a current that was flowing via capacitor  $C_o$ . This current that starts as a step can be found from (1):

$$|I_{ch}| = \omega C_o \left. \frac{dv_{C_0}}{d\vartheta} \right|_{\vartheta_2} = \frac{\pi}{\lambda} \omega C_o V_{C_{OP}} \quad (8)$$

or applying (3):

$$|I_{ch}| = \frac{\pi^3}{\lambda^2} V_{out} \omega C_o \quad (9)$$

The output current  $I_O$  at  $\vartheta_2$  may be written as

$$I_O = |I_{ch}| + \frac{I_m}{n} \sin(\gamma_1) + i_{L_O} \quad (10)$$

where:  $\frac{I_m}{n} \sin \gamma_1$  is the current  $\frac{i_r}{n}$  (Fig.1) at the instant  $\vartheta_2$ ,  $I_m$  is the peak of the input current,  $\gamma_1$  - see Fig. 2 (a), and  $i_{L_O}$  is the inductor  $L_O$  current. The inductor  $L_O$  is shorted by the diodes  $D_1$  and  $D_2$  during the whole interval  $\vartheta_2 \vartheta_3$ . That is why its voltage is practically zero and its current  $i_{L_O}$  has a constant value up to the instant  $\vartheta_3$ , when  $D_1$  turns off. Taking into account this condition, we use  $\vartheta_3$  to derive  $i_{L_O}$ . At  $\vartheta_3$   $i_{C_O} = i_{D_1} = 0$  and therefore:

$$i_{L_O} = \frac{i_r}{n} = \frac{I_m}{n} \sin(\gamma_2) \quad (11)$$

where  $\gamma_2$  - see Fig. 2 (a).

Consequently, the current balance at  $\vartheta_2$  (10) may be written as:

$$I_O = \frac{\pi^3}{\lambda^2} V_{out} \omega C_o + 2 \frac{I_m}{n} \sin\left(\frac{\gamma}{2}\right) \cos\left(\frac{\gamma_1 - \gamma_2}{2}\right) \quad (12)$$

where  $\gamma = \gamma_1 + \gamma_2$  is the overlapping angle:

$$\gamma = \pi - \lambda \quad (13)$$

Taking into account that  $\sin\left(\frac{\gamma}{2}\right) = \cos\left(\frac{\lambda}{2}\right)$  and

assuming that  $\cos\left(\frac{\gamma_1 - \gamma_2}{2}\right) \approx 1$  equation (12) can be simplified to:

$$I_O = \frac{V_{out}}{R_L} = \frac{\pi^3}{\lambda^2} V_{out} \omega C_o + 2 \frac{I_m}{n} \cos\left(\frac{\lambda}{2}\right) \quad (14)$$

From the energy balance it follows that:

$$\frac{V_{in,p} I_m}{2} = \frac{V_{out}^2}{R_L} \quad (15)$$

Solving (6), (14) and (15) together, we obtain the equation for duration of the impulses of the voltage  $v_{C_o}$  in the overlapping mode:

$$\lambda = \sqrt[4]{\pi^5 \omega C_o R_L} \quad (16)$$

In the non-overlapping mode  $\lambda = \pi$ .

Duration of the capacitance  $C_o$  voltage impulses  $\lambda$  as a function of the load factor  $\omega C_o R_L$  based on (16) is depicted in Fig. 3. The rectifier operates in overlapping mode when  $\omega C_o R_L < \frac{1}{\pi}$ .

### B. Real PT ( $R_m > 0$ ).

We assume the followings:

- The voltage across the resonant circuit  $L_r, C_r$  is zero.
- The voltage across  $R_m$  and the first harmonic of the

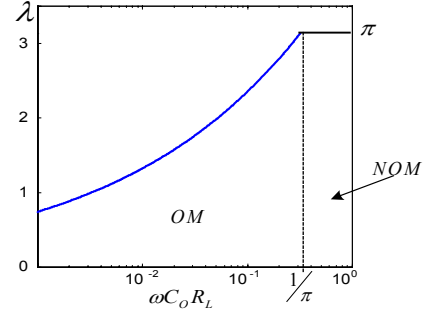


Fig. 3. Duration  $\lambda$  as a function of the normalized load factor  $\omega C_o R_L$ . OM - overlapping mode, NOM- non-overlapping mode.

input voltage of the rectifier are in phase with the input voltage of the PT.

Under these assumptions:

$$V_{in,p} - I_m R_m = \frac{V_{C_o(1)p}}{n} \quad (17)$$

or, according to (4):

$$V_{in,p} - I_m R_m = \frac{4V_{out}}{n} \frac{\cos\left(\frac{\lambda}{2}\right)}{1 - \left(\frac{\lambda}{\pi}\right)^2} \quad (18)$$

It can be shown that equation (14) derived above for the ideal PT, is also correct for the lossy PT. Taking  $\cos\left(\frac{\lambda}{2}\right)$  from (14) and inserting it to (18) we obtain:

$$\frac{V_{in,p} I_m}{2} - \frac{I_m^2 R_m}{2} = \frac{\frac{V_{out}^2}{R_L} - V_{out}^2 \omega C_o \frac{\pi^3}{\lambda^2}}{1 - \left(\frac{\lambda}{\pi}\right)^2} \quad (19)$$

The left side of this equation is the output power, hence (19) may be rewritten as:

$$\frac{V_{out}^2}{R_L} = \frac{\frac{V_{out}^2}{R_L} - V_{out}^2 \omega C_o \frac{\pi^3}{\lambda^2}}{1 - \left(\frac{\lambda}{\pi}\right)^2} \quad (20)$$

Equation (20) can now be used to obtain the angle  $\lambda$ . The solution is identical to (16). We find here that even in the lossy case,  $\lambda$  is independent on the equivalent losses resistance of the PT -  $R_m$ .

### C. The Diodes Losses

In low output voltage rectifiers the voltage drops of the diodes are significant and therefore should be taken into account in the converter's design.

The power losses  $P_D$  in each diode are calculated from equation given in [2]

$$P_D = V_F I_{D(ave)} + R_F I_{D(rms)}^2 \quad (21)$$

where:  $I_{D(ave)}$  and  $I_{D(rms)}$  are the average and the rms diode currents, and  $R_F$  and  $V_F$  are the diode parameters:  $R_F$  is

the equivalent forward resistance and  $V_F$  is the forward voltage:

According to Kirchoff's law, the diodes' currents  $i_{D_1}$  and  $i_{D_2}$  during the overlapping intervals can be described by the following equations:

$$i_{D_1} = i_{L_O} + \frac{i_r}{n} \quad (22)$$

$$i_{D_2} = I_O - i_{L_O} - \frac{i_r}{n} \quad (23)$$

During the non-overlapping intervals, the current of one of the diodes is  $I_O$  and the current of the other diode is zero.

The average diode current  $I_{D(ave)}$  is approximately equal to the half output DC current  $I_{D(ave)} = 0.5I_O$ . The rms diode current  $I_{D(rms)}$  was determined using the assumption that during the overlapping intervals the diode currents are changing linearly.

Applying (9), (13) and (20), following expression of  $I_{D(rms)}$  was obtained:

$$I_{D(rms)} = \frac{I_O}{\sqrt{2}} \varphi(\lambda) \quad (24)$$

where:

$$\varphi(\lambda) = \sqrt{\frac{1}{\pi} \left\{ \left[ \frac{\lambda^2}{\pi^2} + \frac{2}{3} \left( 1 - \frac{\lambda^2}{\pi^2} \right)^2 \right] (\pi - \lambda) + \lambda \right\}} \quad (25)$$

Hence, the general equation of the power losses in each diode  $P_D$  (21) can be rewritten in the following form:

$$P_D = \frac{1}{2} I_O V_F + \frac{1}{2} I_O^2 R_F (\varphi(\lambda))^2 \quad (26)$$

In non-overlapping mode this equation is simplified:

$$P_D^{NOM} = \frac{1}{2} I_O V_F + \frac{I_O^2 R_F}{2} \quad (27)$$

Assuming that the diode's power dissipations is the major power loss, the rectifier efficiency is expressed as:

$$\eta_{rect} = \frac{P_{out}}{P_{out} + 2P_D} \quad (28)$$

where:

$$P_{out} = V_{out} I_O \quad (29)$$

is the output power.

Applying (26) we transform (28) into:

$$\eta_{rect} = \frac{1}{1 + \frac{V_F}{V_{out}} + \frac{R_F (\varphi(\lambda))^2}{R_L}} \quad (30)$$

The value of  $R_F$  in modern diodes is usually small and in most practical cases it is much lower than the load resistance of the rectifier  $R_L$ . This and the fact that the function  $\varphi(\lambda) \leq 1$  for every  $\lambda$  suggest that the term  $R_F (\varphi(\lambda))^2 / R_L$  in the last equation can be neglected. Hence,

$$\eta_{rect} \approx \frac{1}{1 + \frac{V_F}{V_{out}}} \quad (31)$$

As this equation shows, the rectifier efficiency  $\eta_{rect}$  decreases as the output voltage  $V_{out}$  gets lower. It is especially noticeable when  $V_{out}$  is getting closer to the diodes forward voltage  $V_F$ .

#### D. Voltage Range and Power Characteristics of a Real Converter

Applying the power balance condition we can replace the loaded output rectifier by an equivalent resistance  $R_{eq}$  connected to the output of the PT (Fig. 4).

The power balance condition including the rectifier losses can be expressed as:

$$\frac{V_{C_O(1)p}^2}{2R_{eq}} = \frac{V_{out}^2}{R_L} + V_F I_O = \frac{V_{out}^2}{R_L \eta_{rect}} \quad (32)$$

from which:

$$R_{eq} = \left( \frac{V_{C_O(1)p}}{V_{out}} \right)^2 \frac{R_L \eta_{rect}}{2} \quad (33)$$

It was found that the voltage ratio of the last equation could be calculated by an expression, which is similar to (4), but takes into account the rectifier's efficiency:

$$\frac{V_{C_O(1)p}}{V_{out}} = \frac{4}{\eta_{rect}} \left[ \frac{\cos \frac{\lambda^*}{2}}{1 - \left( \frac{\lambda^*}{\pi} \right)^2} \right] \quad (34)$$

The angle  $\lambda^*$  is defined by an expression similar to (16):

$$\lambda^* = 4 \sqrt{\frac{\pi^5 \omega C_o R_L}{\eta_{rect}}} \quad (35)$$

In non-overlapping mode, expressions (33) and (34) converges to:

$$R_{eq}^{NOM} = \frac{\pi^2}{2\eta_{rect}} R_L \quad (36)$$

Applying (31)-(34) we obtain the output to input voltage ratio of a converter with losses in the rectifier and the PT:

$$k_o = \frac{0.25 \eta_{rect} \left[ 1 - \left( \frac{\lambda^*}{\pi} \right)^2 \right]}{\left( 1 + \frac{n^2 R_m}{R_{eq}} \right) \cos \left( \frac{\lambda^*}{2} \right)} \quad (37)$$

The dependences of  $k_{o,ideal}$  (6) and  $k_o$  (37) on the normalized load factor ( $\omega C_o R_L$ ) are depicted in Fig. 5 a, b.

Fig. 5 shows that a decrease in the load factor  $\omega C_o R_L$  causes a decrease of the voltage ratio  $k_o$  in the overlapping mode even in ideal case of a lossless PT ( $R_m = 0$ ), but this

decrease is much more pronounced in the real case ( $R_m > 0$ ,  $P_D > 0$ ).

Fig. 6 depicts the normalized output power

$$P_O^* = \frac{V_{out}^2}{R_L} \frac{2\sqrt{\frac{L_r}{C_r}}}{V_{in,p}^2}$$

as a function of the normalized load factor  $\omega C_o R_L$ .

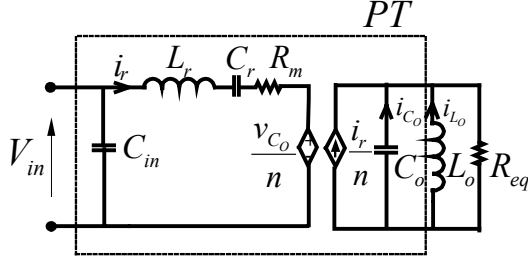


Fig. 4. A simplified equivalent circuit of the converter.

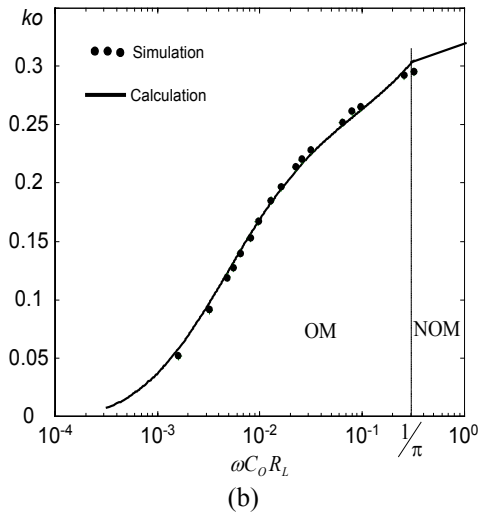
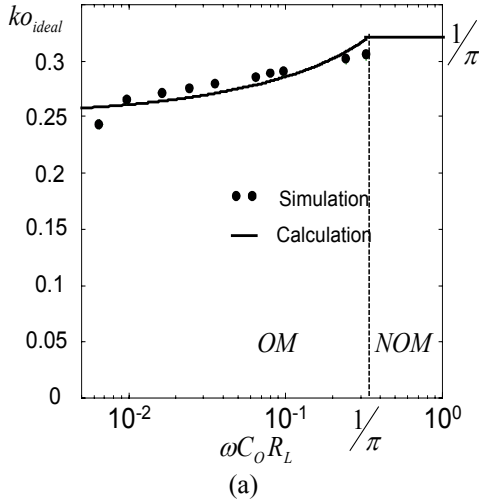


Fig. 5. The voltage ratio as a function of the normalized load factor  $\omega C_o R_L$ : (a) Lossless PT, ideal diodes, (b) Real PT ( $\omega C_o R_m = 0.034$ ), real diodes (MBR160P). The peak input voltage  $V_{in,p} = 30V$ . OM – overlapping mode, NOM – non-overlapping mode.

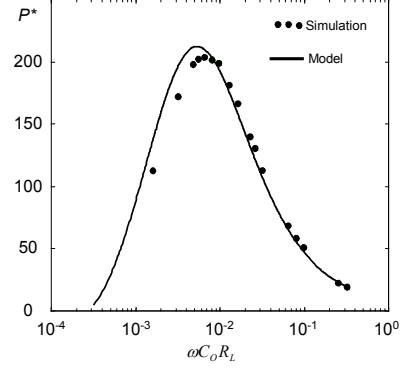


Fig. 6. The normalized output power  $P^*$  as a function of the normalized load factor  $\omega C_o R_L$ . Real PT and real diodes (the same parameters as in Fig. 5 b).

Efficiency of the PT  $\eta_{PT}$  and efficiency of the whole converter  $\eta$  can be also easily calculated if we know  $R_{eq}$ :

$$\eta_{PT} = \frac{R_{eq}}{n^2 R_m + R_{eq}} \quad (38)$$

$$\eta = \frac{P_{out}}{P_{in}} = \eta_{PT} \eta_{rect} \quad (39)$$

#### IV. EXPERIMENTAL RESULTS

Philips PT (RT 35x8x2 PXE43-S) with thickness polarization mode was used in the experiment. Its main parameters (Fig. 1) were measured to be  $L_r = 165mH$ ,  $C_r = 15.1pF$ ,  $C_{in} = C_o = 510pF$ ,  $R_m = 105\Omega$ ,  $n = 1$ . Operation frequency was equal to the resonant frequency. The parallel resonant inductance was  $L_o = 4.88mH$  and the diodes were a Schottky diode (MBR160P). The experiments were carried out for a load resistance  $R_L$  range of  $30\Omega$  to  $1k\Omega$ . The range of the peak of the input voltage was  $V_{in,p} = 5 - 30V$ . The experimental and the theoretical voltage ratios as a function of the load resistance are shown in Fig. 7. It is evident that the analytical equations and characteristics, derived in this study, are in excellent agreement with simulation and experimental results

#### V. DISCUSSION AND CONCLUSIONS

It was shown that the PT power converter with a halfway two diodes rectifier can operate in two modes: NOM - the operational mode described earlier in which there is no overlap between the conduction intervals of the diodes, and OM – the newly uncovered mode with overlap between the conduction intervals of the diodes. It was found that the operation mode is depending on the normalized load factor  $\omega C_o R_L$ . The load factor is a function of the PT parameters and the load resistance.

The study highlights the effect of the load and parasitic resistances on the output voltage and the losses for both modes. The analytical investigations were supported by simulation and experiment results, and found to be in excellent agreement.

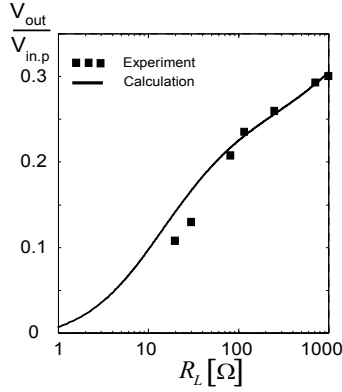


Fig. 7 Experimental and theoretical voltage ratio  $V_{out}/V_{in,p}$  as a function of the load resistance  $R_L$ .  $V_{in,p}=30V$ ,  $\omega C_o R_m=0.034$ .

It is important to note that a design that is based on the known NOM may be in a considerable error if the rectifier operates in OM.

The analytical equations derived in this study can be used in engineering design. An example of a design procedure is given in the Appendix. In this design example we assume that the PT is given and calculate the required input voltage to meet the out specifications ( $P_{out}$ ,  $V_{out}$ ). If the calculated input voltage is not equal to the available input source, a trial and error procedure need to be following until the correct PT is found. Alternatively, the PT parameters (e.g.  $n$ ) can be adjusted to meet the requirement and by this define the set of parameters of the PT that will meet the given specifications.

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#### APPENDIX

##### Design Guidelines

Given: the AC/DC PT converter output requirements ( $V_{out}$ ,  $P_{out}$ ), the PT parameters ( $L_r$ ,  $C_r$ ,  $C_{in}$ ,  $C_o$ ,  $R_m$ ,  $n$ ), and the diodes to be used in converter.

Variables to be evaluated: the input voltage  $V_{in}$  that ensures the required output attributes of the power converter and the input power  $P_{in}$ .

##### Design steps:

- 1) Define the resonant frequency  $\omega_r$ , the load resistance  $R_L$ , the resonant inductance  $L_o = \frac{L_r C_r}{C_o}$  and the load factor  $\omega C_o R_L$  from the output specifications and the PT parameters.
- 2) Find the forward diode voltage  $V_F$  from data sheet and evaluate the rectifier efficiency  $\eta_{rect}$  (31).
- 3) Calculate the parameter  $\lambda^*$  (35). The rectifier is operating in non-overlapping mode when  $\lambda^* = \pi$  and in overlapping mode when  $\lambda^* < \pi$ .
- 4) Define the equivalent load resistance of the converter  $R_{eq}$  (33) and (34).
- 5) Obtain the voltage ratio  $k_o$  of the real converter (37).
- 6) Calculate the peak input voltage as  $V_{in(p)} = \frac{V_{out}}{k_o}$ .
- 7) Find the PT and the whole converter efficiencies  $\eta_{PT}$  and  $\eta$  (38), (39).
- 8) Determine the input power  $P_{in} = \frac{P_{out}}{\eta}$ .